

## electronics-lis

**IMCS (Intelligent Motion Control System)** 

## The **IMCS** includes three main parts:

1. Power Supervisor Unit (**PSU**) one for each application. Its main goal is to control the Emergency Stop and Enable wired loops but also power supplies

2. Integrated and versatile Intelligent Motion Control Unit (IMCU) one for each actuator. In this case, the IMCU combines all functions necessary to "local/individual" control of one actuator, including: DSP (PIC32MK) and CPLD, Power amplifier in DC or PWM technologies and several Communication interfaces

3. Accessories as back planes, standard rack, connectors etc.

The **IMCS** is a cost and time effective solution to implement complex and high performance motion control/test systems or prototypes.

It constitutes a family of **ready-to-use** hardware and firmware components. A bespoke solution can be quickly and easily assembled from these components, corresponding to a particular combination of actuators and sensors.

## The IMCU includes:

1. Common MAIN board including floating-point DSP (PIC32MK) and (CPLD) to interface external mezzanine boards and power amplifier



The (**PSU**) includes: 1. Internal supplies for electronic

2. Enable and State loops management and interconnection (CPLD) with power supply control

3. Power management including DC or AC felay

4. **Isolated digital I/O** applied to interface limits switches, emergency button, additional elies etc.

5.On/Off and state of Enable/State Loops to be connected to the Host, PMAC, Galil/PLC etc.

6.Internal (rack) temperature control

7.Interconnection with **Raspberry PI** to provide Ethernet, Web micro-server, USB etc.

2. Customized MEZZanine to interface the particular sensors such as resolver, LVDT, incremental etc. for a specific application.

3. Range of **Power Amplifier** (s) (linear or PWM) for voice-coil, Brushless, step, DC and AC motors. It includes analogue measurements and several configurable protections.

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